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1 % The Directional Mobility Index, computed by "DMMtool.m", has been designed
2 % by C. Ferretti and P. Ganugi; it is thoroughly explored in the paper:
3 % "A new mobility index for transition matrices", C.Ferretti and P.Ganugi,
4 % Statistical Methods & Applications 22 (3), 403-425.
5 % "DMMtool.m" is freely downloadable from the Mathworks's page
6 % dedicated to file exchange:
7 % www.mathworks.com/matlabcentral/fileexchange/
8 %
9 clear License response ans
10 License=char({' ' Copyright © Danilo Aringhieri, Camilla Ferretti, 2017. ' ,...
11 ' This software is released under the license ' ' Creative Commons Unported, ' ,...
12 ' Attribution – Non Commercial – Share Alike 4.0 ' ' (CC BY – NC – SA 4.0) ' ,...
13 ' whose readable summary is displayed at: ' ,...
14 ' http://creativecommons.org/licenses/by-nc-sa/4.0/ ' ,...
15 ' and whose legal text is available at the following webpage: ' ,...
16 ' http://creativecommons.org/licenses/by-nc-sa/4.0/legalcode ' ,''});
17 disp(License)
18 disp(' Press the "Enter" button on the keyboard to START...')
19 response=input(' 's');
20 while isempty(response)==0
21 disp(' Please, press just the "Enter" button to START!')
22 response=input(' 's');
23 end
24 Intro1=char({' ' This is a MATLAB command line interface (R2006a at least) ' ,...
25 ' for the estimation of the Directional Mobility Index based on raw data ' ,...
26 ' for a sample of statistical units respect to a quantitative variable, ' ,...
27 ' like any size-specific variable (as income in case of families; ' ,...
28 ' revenues or the number of employees, in case of firms, etc.). ' ,...
29 ' The not-normalized Directional Mobility Index is defined by: ' ,'' ,...
30 '  $I_{w_v}(P) = \sum_{i=1..n} w_i * [\sum_{j=1..n} P_{i_j} * \text{sign}(j-i) * v(|j-i|)]$  ' ,...
31 ' , If we name its minimum as  $m1 = \sum_{i=1..n} w_i * v(1-i)$  ' ,...
32 ' and its maximum as  $m2 = \sum_{i=1..n} w_i * v(n-i)$  ' ,...
33 ' then the normalized version, respect to  $[-1, +1]$ , of the Index is: ' ,'' ,...
34 '  $I_{norm\_w_v}(P) =$  ' ,...
35 '  $= \{ [-I_{w_v}(P)/m1 \text{ if } I_{w_v}(P)<0] \text{ and } [I_{w_v}(P)/m2 \text{ if } I_{w_v}(P)>=0] \}$  ' ,...
36 ' , The summations are computed over a discrete set  $\{1,2,..,n\}$  ' ,...
37 ' of n states accessible to every individual of the sample ' ,...
38 ' which evolves randomly from the initial state "i" to the final state "j" ' ,...
39 ' with conditional probability  $P_{i_j}$  , according to the transition matrix "P". ' ,...
40 ' Each state may be a class grouping several different values of the variable. ' ,...
41 ' ( press the "Enter" button to continue about this Index ) '});
42 disp(Intro1)
43 response=input(' 's');
44 while isempty(response)==0
45 disp('(please, press [Enter] !)')
46 response=input(' 's');
47 end
48 Intro2=char({' ' Parameters  $\{w_i\}$  are to be chosen properly to weight ' ,...
49 ' the contribution of the starting state "i" to the mobility index. ' ,...
50 ' Similarly, the role of the function  $v(|j-i|)$  is to measure, ' ,...
51 ' for the mobility, the importance of the phase-jump intensity  $|j-i|$  ' ,...
52 ' while the factor  $\text{sign}(j-i)$  accounts for the jump orientation. ' ,...
53 ' , This tool does not work ' ,...
54 ' if data consist of qualitative categories ' ,...
55 ' of a non-quantitative statistical variable !! ' ,...
56 ' It is able to process any panel data for a single variable ' ,...
57 ' known at least in two different periods of time (decades, years, months..., ' ,...
58 ' according to the frequency of observations). ' ,...
59 ' , During the execution of this tool, ' ,...
60 ' YOU WILL BE ASKED TO INSERT YOUR FAVOURITE VALUES OR SHAPES ' ,...
61 ' for all the parameters and functions appearing in the Index expression, ' ,...
62 ' , ARE YOU INTERESTED in USING IT ? ' ,...
63 ' (Possible answers: "Y" for "Yes" or "N" for "Not", ' ,...
64 ' then press the "Enter" button) ' ,...

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65 ' Beware that, if you answer "Yes", all the objects ',...
66 ' from the previous run of this tool,',...
67 ' WILL BE CANCELLED !! ');
68 disp(Intro2)
69 response=input(' ','s');
70 while strcmp(response',{'Y','y','N','n'})==[0,0,0,0]
71     disp(' (You must answer exclusively "Y" or "N" !) ')
72     response=input(' ','s');
73 end
74 if sum(strcmp(response,{'N','n'}))==1
75 disp(char({' ',' OK: you are going to return directly ',...
76 ' to the prompt state in the Command Window! ',' '}))
77 clear License Intro1 Intro2 response
78 return
79 elseif sum(strcmp(response,{'Y','y'}))==1
80 disp(char({' ',' BE CAREFUL !!! '}))
81 end
82 Intro3a=char({' ',' The following PRESCRIPTIONS MUST BE SATISFIED. ',...
83 ' ',' I°] ',...
84 ' A spreadsheet, able to read and save xls-type or xlsx-type files, ',...
85 ' has to be installed on your computer (Windows Excel would be better ',...
86 ' but a free opensource saving into xlsx format goes quite well anyway, ',...
87 ' like Calc from LibreOffice). ',...
88 ' Here, for every statistical unit, the variable values, ',...
89 ' to be imported into MATLAB, must be tabled by columns and rows. ',...
90 ' ',' II°] ',...
91 ' Verify that the Current Folder, on the top of the MATLAB Home GUI,',...
92 ' is the one containing both your Excel data file and the script of this interface; ',...
93 ' otherwise leave this tool, put the data and the script into the same folder ',...
94 ' then run again. ',...
95 ' (press [Enter] to go on...) ');
96 disp(Intro3a)
97 response=input(' ','s');
98 while isempty(response)==0
99 disp('(please, press [Enter]...')
100 response=input(' ','s');
101 end
102 Intro3b=char({' ' III°] ',...
103 ' From some point onwards in your datasheet, to each row should correspond ',...
104 ' the sequence of numerical values of a particular individual ',...
105 ' relative to the variable for all the dates of survey; ',...
106 ' in every column, all units" values must be listed referring to a specific period. ',...
107 ' Actually, opening columns on the left may be filled with some lists of strings ',...
108 ' (firms" names in alphabetic characters, alphanumeric identity codes or addresses ) ',...
109 ' and the opening rows on the top may be filled with the dates of observations ',...
110 ' or any other details written in string characters. ',...
111 ' DO YOU WANT TO CONTINUE ? ',...
112 ' (Answer "Y" for "Yes" or "N" for "Not", then press [Enter]) ');
113 disp(Intro3b)
114 response=input(' ','s');
115 while strcmp(response,{'Y','y','N','n'})==[0,0,0,0]
116     disp(' (You must answer exclusively "Y" or "N" !) ')
117     response=input(' ','s');
118 end
119 if sum(strcmp(response,{'N','n'}))==1
120 disp(char({' ',' OK: you are going to return directly ',...
121 ' to the prompt state in the Command Window! ',' '}))
122 clear Intro1 Intro2 Intro3a Intro3b License response
123 return
124 elseif sum(strcmp(response,{'Y','y'}))==1
125 clear Intro1 Intro2 Intro3a Intro3b
126 end
127 clear k h filename AuxData1 Titles dimensions notAvail unavail_id Sz AuxData2 MatData resp dim Min_Sizes
128 clear Max_Sizes sup units lowest_datum highest_datum classes_number num_k_Lstart_Lend w_k_Lstart_Lend

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129 clear v V_k_h Number_k_h Lstart_Lend P_k_h Lstart_Lend P_k_h Tstart_Tend num_tot_Lstart_Lend
130 clear Pup_k_h Lstart_Lend Pup_k_h Tstart_Tend Pdn_k_h Lstart_Lend Pdn_k_h Tstart_Tend w_k sum_w_k
131 clear Tstart_Tend m1 m2 Lstart_Lend Y_V_k Lstart_Lend Y_V_k Tstart_Tend ImmobilShares_k Tstart_Tend
132 clear Yup_V_k Lstart_Lend Yup_V_k Tstart_Tend Ydn_V_k Lstart_Lend Ydn_V_k Tstart_Tend ImmobilShares_k Lstart_Lend
133 clear I_w_V Lstart_Lend I_w_V Tstart_Tend Iup_w_V Lstart_Lend Iup_w_V Tstart_Tend Idn_w_V Lstart_Lend
Idn_w_V Tstart_Tend
134 clear Inorm_w_V Lstart_Lend Inorm_w_V Tstart_Tend Inorm_up_w_V Lstart_Lend Inorm_up_w_V Tstart_Tend
135 clear Inorm_dn_w_V Lstart_Lend Inorm_dn_w_V Tstart_Tend resp_w last_ans V_infinite V_real V_nan
136 clear UPvsDN_w_V Tstart_Tend UPvsDN_w_V Lstart_Lend
137 clear Itrace_Tstart_Tend Idet_Tstart_Tend I2nd_eigval_Tstart_Tend Ieigvals_Tstart_Tend Ipredict_Tstart_Tend
138 clear abs_eigenvals_Tstart_Tend sorted_abs_eigenvals_Tstart_Tend eigenvects_Tstart_Tend eigenvals_Tstart_Tend
139 clear Intensity_k_h I_2ndBarthol_Tstart_Tend BMorrDN_Tstart_Tend BMorrUP_Tstart_Tend w_k Tstart_Tend
140 Input0=char({' ',' ' [Consider that you CAN STOP AT ANY TIME the run of this program ',...
141 ' TYPING "Ctrl" + "C" ON THE KEYBOARD !!!] ',' ');
142 Input0bis=char({' ',' ' (You CAN STOP AT ANY TIME the program ',...
143 ' TYPING "Ctrl" + "C" ON THE KEYBOARD !!!) ');
144 disp(Input0)
145 Input1=char({' ',' ' In order to import automatically your data, ',...
146 ' WRITE JUST THE NAME OF YOUR FILE, ',...
147 ' including its extension (".xls" or ".xlsx"), ',...
148 ' then press [Enter]. ',...
149 ' (any other command will provide an error message as a result; ',...
150 ' if it should appear a warning message, please wait few seconds. ');
151 disp(Input1)
152 filename=input(' ','s');
153 [AuxData1,Titles]=xlsread(filename);
154 dimensions=size(AuxData1);
155 for k=1:dimensions(2)
156     notAvail(k)=(sum(isnan(AuxData1(:,k))))./dimensions(1);
157 end
158 unavail_id=find(notAvail-1);
159 Sz=size(unavail_id);
160 AuxData2=AuxData1(:,[unavail_id]);
161 Names1=char({' ',' ' This tool tolerates the existence in the original datasheet of some columns ',...
162 ' filled with numbers which ARE NOT NUMERICAL DATA, ',...
163 ' like when the statistical units are indentified (also) by numbers. ',...
164 ' ALL these kind of numerical non-data columns ',...
165 ' HAVE TO STAY AT THE LEFT of the variable values !! ',...
166 ' Do some numerical non-data columns exist in the original datasheet? ',...
167 ' ( Answer "Y" if they exist or "N" otherwise, then press [Enter] ) ');
168 disp(Names1)
169 response=input(' ','s');
170 while strcmp(response,{'Y','y','N','n'})==[0,0,0,0]
171     disp(' (You must answer exclusively "Y" or "N" ! ) ')
172     response=input(' ','s');
173 end
174 if sum(strcmp(response,{'N','n'}))==1
175     MatData=AuxData2;
176 elseif sum(strcmp(response,{'Y','y'}))==1
177     Names2=char({' ',' ' How many are the numerical non-data columns in the original sheet ? ');
178     disp(Names2)
179     nondata_col=input(' ');
180     if (isscalar(nondata_col)==0 | isreal(nondata_col)==0 | isnan(nondata_col)==1 | isinf(nondata_col)==1 | nondata_col<0 |
floor(nondata_col)~=nondata_col)
181     while (isscalar(nondata_col)==0 | isreal(nondata_col)==0 | isnan(nondata_col)==1 | isinf(nondata_col)==1 | nondata_col<0 |
| floor(nondata_col)~=nondata_col)
182         if isscalar(nondata_col)==0
183             disp(' ( You pressed the [ENTER] button or inserted a vector or an array ! ) ')
184             disp(' BUT you must insert exclusively a positive integer ! ) ')
185             nondata_col=input(' ');
186         elseif (isscalar(nondata_col)==1 & (isnan(nondata_col)==1 | isinf(nondata_col)==1 | isreal(nondata_col)==0))
187             disp(' Your input is a NaN value or infinite or a complex number: WHY? ')
188             nondata_col=input(' ');
189         elseif nondata_col<0

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190     disp(' ( You must insert exclusively a positive number ! ) ')
191     nondata_col=input(' ');
192     elseif (nondata_col>0 & floor(nondata_col)~=nondata_col)
193         disp(' ( You must insert exclusively a positive integer ! ) ')
194         nondata_col=input(' ');
195     end
196 end
197 elseif (isscalar(nondata_col)==1 & isreal(nondata_col)==1 & isnan(nondata_col)==0 & isinf(nondata_col)==0 & ✓
nondata_col>0 & floor(nondata_col)==nondata_col)
198 end
199 MatData=AuxData2(:,nondata_col+1:Sz(2));
200 end
201 clear Names1 Names2 AuxData1 AuxData2 notAvail unavail_id Sz nondata_col
202 dim=size(MatData);
203 Max_Sizes=max(MatData);
204 Min_Sizes=min(MatData);
205 disp(char({' ',' What is the dimensional unit of your data? ','...
206 '( Use the expression you like and press [Enter] ')))
207 units=input(' ','s');
208 Input2_1=char({'',' Observation dates will be implicitly marked ','...
209 ' by progressive positive integers ','...
210 ' according to the position of each detection in the sequence. ','...
211 ' These integers will be assigned to two auxiliary variables: ','...
212 ' "Lstart" (when a transition starts) and "Lend" (when a transition ends). ','...
213 ',' All the numerical data from your file ','...
214 ' will be recorded into the matrix "MatData" in the workspace. ','...
215 ' The strings will be copied in an array named "Titles" ','...
216 '( it will be cancelled soon after). ','...
217 ' The "NaN" elements inside "MatData" correspond, inside the spreadsheet, ','...
218 ' to empty cells or to cells filled with string characters. ','...
219 '( press [Enter] to go on...) ');
220 disp(Input2_1)
221 response=input(' ','s');
222 while isempty(response)==0
223     disp('(press [Enter] to go on...)')
224     response=input(' ','s');
225 end
226 Input2_2=char({'',' Three vectors will be created, ','...
227 ' named "dim", "Max_Sizes" and "Min_Sizes": ','...
228 ',' "dim" consists of the dimensions of MatData:','...
229 ' dim(1) is the number of statistical units enumerated inside the datasheet. ','...
230 ' dim(2) is the number of periods when the variable's values have been measured. ','...
231 ',' " Max_Sizes " and " Min_Sizes " are row vectors: ','...
232 ' " Max_Sizes(m) " and " Min_Sizes(m) " are respectively ','...
233 ' the biggest datum and the smallest one registered in the m-th column of "MatData" ','...
234 ' referring to the m-th observation period. ','...
235 '( press [Enter] to see) ','');
236 disp(Input2_2)
237 clear resp
238 response=input(' ','s');
239 while isempty(response)==0
240     disp('(press [Enter] to see)')
241     response=input(' ','s');
242 end
243 disp(' According to your sample, the vector " Min_Sizes " is: ')
244 if dim(2)==2
245     fprintf(' [%-1.3f, ',Min_Sizes(1));...
246     fprintf('%-1.3f] \n',Min_Sizes(2))
247 else
248     fprintf(' [%-1.3f, ',Min_Sizes(1));...
249     fprintf('%-1.3f, ',Min_Sizes(2:dim(2)-1));...
250     fprintf('%-1.3f] \n',Min_Sizes(dim(2)))
251 end
252 disp(' and the vector " Max_Sizes " is: ')

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253 if dim(2)==2
254 fprintf('   [%-1.3f, 'Max_Sizes(1));...
255 fprintf('%-1.3f] \n',Max_Sizes(2))
256 else
257 fprintf('   [%-1.3f, 'Max_Sizes(1));...
258   fprintf('%-1.3f, 'Max_Sizes(2:dim(2)-1));...
259   fprintf('%-1.3f] \n',Max_Sizes(dim(2)))
260 end
261 clear Titles
262 lowest_datum=min(Min_Sizes');
263 highest_datum=max(Max_Sizes');
264 fprintf(' (all the values are "%s") \n',units)
265 disp(' ')
266 disp(' In your whole spreadsheet, absolute minimum and maximum values are: ')
267 fprintf(' Minimal datum = %-1.3f \n',lowest_datum)
268 fprintf(' Maximal datum = %-1.3f \n',highest_datum)
269 fprintf('          (%s) \n',units)
270 disp('          (Press [Enter] to continue...) ')
271 response=input(' ','s');
272 while isempty(response)==0
273 disp('(press [Enter] to continue...')
274 response=input(' ','s');
275 end
276 Input3=char({'',' ALL FIRMS are going to be GROUPED ',...
277 ' IN CLASSES OF DIFFERENT WIDTH, ',...
278 ' splitting the whole domain of the variable values ',...
279 ' in the following manner: '...
280 ','[lowest datum;sup(1)], (sup(1);sup(2)], (sup(2);sup(3)],..., (sup(n-1);highest datum] ',...
281 ',' Each class represents one of the states among which a transition happens ',...
282 ' and will be identified by a progressive positive integer. ',...
283 ',' INSERT THE NUMBER OF CLASSES ',...
284 ' and press [Enter]. ');
285 disp(Input3)
286 classes_number=input(' ');
287 while (isscalar(classes_number)==0 | isnan(classes_number)==1 | isinf(classes_number)==1 | classes_number<=0 | floor↵
(classes_number)~=classes_number...
288   | isreal(classes_number)==0)
289   if isscalar(classes_number)==0
290     disp(' ( You pressed the [ENTER] button or inserted a vector or an array ! ) ')
291     disp(' BUT you must insert exclusively a positive integer ! ) ')
292     classes_number=input(' ');
293   elseif (isscalar(classes_number)==1 & (isnan(classes_number)==1 | isinf(classes_number)==1 | isreal(classes_number)↵
==0))
294     disp(' Your input is a NaN value or a not finite one or it is not a ral number: WHY? ')
295     classes_number=input(' ');
296   elseif classes_number<=0
297     disp(' ( You must insert exclusively a positive number ! ) ')
298     classes_number=input(' ');
299   elseif (classes_number>0 & floor(classes_number)~=classes_number)
300     disp(' ( You must insert exclusively a positive integer ! ) ')
301     classes_number=input(' ');
302   end
303 end
304 disp(' ')
305 fprintf(' Now write the sup for everyone of the first %-1.0d classes, \n',classes_number-1)
306 disp(' which are the inner points of your partition of the domain [ Minimal datum, Maximal datum ] ')
307 disp(' (the last class is excluded because its sup is the Maximal datum just above) ')
308 disp(' BE CAREFUL NOT TO ROLL OUT the ENTER button if you don"t want to quit !! ')
309 for k=1:classes_number-1
310   fprintf('Insert the top (expressed as number of "%s") of the %-1.0d° class:\n',units,k)
311   sup(k)=input(' ');
312   if k==1 & sup(1)>lowest_datum & sup(1)<highest_datum
313     continue
314   elseif k==1 & (sup(1)<=lowest_datum | sup(1)>=highest_datum)

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315 while (sup(1)<=lowest_datum | sup(1)>=highest_datum)
316     if sup(1)<=lowest_datum
317         disp(char({' ERROR!! ',...
318             ' Insert a value bigger than Minimal datum (and smaller than Maximal datum): '}))
319         sup(1)=input(' ');
320     elseif sup(1)>=highest_datum
321         disp(char({' ERROR!! ',...
322             ' Insert a value smaller than Maximal datum (but bigger than Minimal datum): '}))
323         sup(1)=input(' ');
324     end
325 end
326 continue
327 end
328 %
329 if (sup(k)>lowest_datum & sup(k)>sup(k-1) & sup(k)<highest_datum)
330     continue
331 elseif (sup(k)<=lowest_datum | sup(k)<=sup(k-1) | sup(k)>=highest_datum)
332     while (sup(k)<=lowest_datum | sup(k)<=sup(k-1) | sup(k)>=highest_datum)
333         if sup(k)<=lowest_datum
334             disp(char({' ERROR!! ',...
335                 ' Insert a value bigger than Minimal datum (but smaller than Maximal datum): '}))
336             sup(k)=input(' ');
337         elseif sup(k)>=highest_datum
338             disp(char({' ERROR!! ',...
339                 ' Insert a value smaller than Maximal datum (and bigger than Minimal datum): '}))
340             sup(k)=input(' ');
341         elseif sup(k)<=sup(k-1)
342             disp(char({' ERROR!! ',...
343                 ' Insert a value greater than the previous one '}))
344             sup(k)=input(' ');
345         end
346     end
347 end
348 end
349 Extrm=[lowest_datum,sup,highest_datum];
350 Input4=char({' ',' The extremes of the partition you have chosen ',...
351 ' are arranged orderly as components inside the vector named "Extrm". ',' '});
352 disp(Input4)
353 %
354 % num_k_Lstart_Lend is the number of units belonging to the k-th class
355 %         in the early period (Lstart) and having a numerical datum
356 %         in the final period (Lend).
357 % w_k_Lstart_Lend(k) is the new name of the former weight "w_i"
358 %         for any k-th class as a transition starting state.
359 %         It is defined as the percentage of units inside the k-th class
360 %         in the early period with an available datum in the final period.
361 %
362 % In some spreadsheets it may happen
363 % some units are lacking of information at some dates.
364 % ANY UNIT, WITHOUT A DEFINED FINAL VALUE FOR THE VARIABLE,
365 % WILL BE EXCLUDED FROM THE COMPUTATION !!
366 % The matrix "isnan_data" serves for this purpose.
367 %
368 clear dimensions Input0 Input1 Input2_1 Input2_2 Input3 Input4
369 isnan_data=isnan(MatData);
370 num_k_Lstart_Lend=zeros(classes_number,dim(2)-1,dim(2)-1);
371 num_tot_Lstart_Lend=zeros(dim(2)-1,dim(2)-1);
372 for Lstart=1:dim(2)-1
373     for Lend=Lstart+1:dim(2)
374         num_k_Lstart_Lend(1,Lstart,Lend)=sum(MatData(:,Lstart)<=sup(1) & isnan_data(:,Lend)==0);
375     for k=2:classes_number-1
376         num_k_Lstart_Lend(k,Lstart,Lend)=sum(MatData(:,Lstart)>sup(k-1) & MatData(:,Lstart)<=sup(k) & isnan_data(:,Lend)==0);
377     end % (for "k")
378     num_k_Lstart_Lend(classes_number,Lstart,Lend)=sum(MatData(:,Lstart)>sup(classes_number-1) & isnan_data(:,Lend)==0);

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379 end %(for "Lend")
380 end %(for "Lstart")
381 for Lstart=1:dim(2)-1
382 for Lend=Lstart+1:dim(2)
383 num_tot_Lstart_Lend(Lstart,Lend)=sum(num_k_Lstart_Lend(:,Lstart,Lend));
384 end
385 end
386 default=char({' By default the weights {w_i} are the rates of individuals ',...
387 ' starting a transition from the state "i" at time Tstart ',...
388 ' to reach anyone of the states at time Tend. ',...
389 ' If you want to change, it is possible to assign a number, ',...
390 ' different from the starting probability, ',...
391 ' weighting every single initial state "i" inside the Index; ',...
392 ', Do you want to modify the default weights? ',...
393 ' ( "Y" for "Yes" or "N" for "Not", then [Enter] ) });
394 Input_5ter=char({' ', ' Lastly write, in the command line, the handle " @(x) " ',...
395 ' followed by the mathematical shape of your v(|i-j|), ',...
396 ' according to the MATLAB coding for operations and functions: ',...
397 ' for example @(x)exp(x^(1/3)) or @(x)log(2*x^3) . ',...
398 ' You can express it respect to the auxiliary variable "x", ',...
399 ' so that x = |i-j| : anyway, to avoid conflicts, ',...
400 ' you must refer the handle "@" and the function to the same variable. ', '});
401 disp(default)
402 resp_w=input(' ', 's');
403 while strcmp(resp_w,{'Y','y','N','n'})==[0,0,0,0]
404 disp(' (You must answer exclusively "Y" or "N" ! ) ')
405 resp_w=input(' ', 's');
406 end
407 if sum(strcmp(resp_w,{'N','n'}))==1
408 for Lstart=1:dim(2)-1
409 for Lend=Lstart+1:dim(2)
410 w_k_Lstart_Lend(1,Lstart,Lend)=num_k_Lstart_Lend(1,Lstart,Lend)./sum(MatData(:,Lstart)>=lowest_datum & isnan_data(:,Lend)==0);
411 for k=2:classes_number-1
412 w_k_Lstart_Lend(k,Lstart,Lend)=num_k_Lstart_Lend(k,Lstart,Lend)./sum(MatData(:,Lstart)>=lowest_datum & isnan_data(:,Lend)==0);
413 end %(for "k")
414 w_k_Lstart_Lend(classes_number,Lstart,Lend)=num_k_Lstart_Lend(classes_number,Lstart,Lend)./sum(MatData(:,Lstart)>=lowest_datum & isnan_data(:,Lend)==0);
415 end %(for "Lend")
416 end %(for "Lstart")
417 elseif sum(strcmp(resp_w,{'Y','y'}))==1
418 change=char({' If you desire to decide which scalar weights each initial state, ',...
419 ' not belonging to the starting distribution, BEWARE that ',...
420 ' THE SUM OVER ALL THE STATES MUST BE EQUAL TO 1. ',...
421 ', If you dislike the option about {w_i} ',...
422 ' you have to modify directly the part of this script concerning definitions ',...
423 ' of " w_k_Lstart_Lend(k,Lstart,Lend) ". ',...
424 ', BE also CAREFUL NOT TO PINCH the ENTER button if you don"t want to quit !!});
425 disp(change)
426 for k=1:classes_number
427 fprintf('Insert the numerical value of the %-.10d° weight w(%-.10d):\n',k,k)
428 w_k(k)=input(' ');
429 while w_k(k)<0 || w_k(k)>1 || isnan(w_k(k))==1 || isreal(w_k(k))==0 || isscalar(w_k(k))==0
430 if w_k(k)<0
431 disp(' This input is a probability: you have to insert a positive number !! ')
432 w_k(k)=input(' ');
433 elseif w_k(k)>1
434 disp(char({' This input is a probability of a single event: ',...
435 ' it cannot be a number greater than 1 !! '}))
436 w_k(k)=input(' ');
437 elseif (isnan(w_k(k))==1 || isscalar(w_k(k))==0)
438 disp(' This input is a probability: you have to insert a scalar !! ')
439 w_k(k)=input(' ');

```



```

440 elseif isreal(w_k(k))==0
441     disp(' This input is a probability: you have to insert a real scalar !! ')
442     w_k(k)=input(' ');
443 end
444 end
445 end
446 sum_w_k=single(sum(w_k));
447 if (sum_w_k>1 | sum_w_k<1)
448 while (sum_w_k>1 | sum_w_k<1)
449 warn=char({' Pay attention: ',...
450 ' THE SUM OF ALL THE PREVIOUS INPUTS IS NOT EQUAL TO 1 !! ',...
451 ' YOU NEED TO INSERT ALL THE WEIGHTS AGAIN. ','',...
452 ' Be careful not to pinch the enter button !});
453 disp(warn)
454 for k=1:classes_number
455 fprintf('Insert the numerical value of the %-.10d° weight w(%-.10d):\n',k,k)
456 w_k(k)=input(' ');
457 while w_k(k)<0 || w_k(k)>1 || isnan(w_k(k))==1 || isreal(w_k(k))==0 || isscalar(w_k(k))==0
458     if w_k(k)<0
459         disp(' This input is a probability: you have to insert a positive number !! ')
460         w_k(k)=input(' ');
461     elseif w_k(k)>1
462         disp(char({' This input is a probability of a single event: ',...
463 ' it cannot be a number greater than 1 !! '}))
464         w_k(k)=input(' ');
465     elseif (isnan(w_k(k))==1 || isscalar(w_k(k))==0)
466         disp(' This input is a probability: you have to insert a scalar !! ')
467         w_k(k)=input(' ');
468     elseif isreal(w_k(k))==0
469         disp(' This input is a probability: you have to insert a real scalar !! ')
470         w_k(k)=input(' ');
471     end
472 end
473 end
474 sum_w_k=single(sum(w_k));
475 end
476 else
477 end
478 for Lstart=1:dim(2)-1
479     for Lend=Lstart+1:dim(2)
480         for k=1:classes_number
481 w_k_Lstart_Lend(k,Lstart,Lend)=w_k(k);
482         end
483     end
484 end
485 end
486 disp(Input_5ter)
487 %
488 % It is applied the classical definition of Laplace and Bernoulli
489 % (the number of favorable cases divided by the number of all possible cases)
490 % to estimate, by the data sample, the following:
491 %
492 % P_k_h_Lstart_Lend(k,h,Lstart,Lend) which is the probability that a statistical unit may make a transition
493 % from the initial k-th class to the final h-th one, reached in the Lend-th period.
494 %
495 % In " P_k_h_Lstart_Lend " the divider of the ratio (the number of all possible cases)
496 % is the number of all units completing a transition between Lstart and Lend,
497 % whatever the initial status and the destination.
498 % The top of the same ratio is:
499 %
500 % Number_k_h_Lstart_Lend(k,h,Lstart,Lend) that is the number of units moving from the state
501 % named as "k", occupied at time Lstart, to the state "h",
502 % where they are observed at time Lend.
503 %

```



```

504 %
505 % We are also going to introduce
506 %
507 % V_k_h(h,k) the suitable function of the difference (h-k), weighting for the index
508 % the significance of a jump from the k-th class to the h-th one
509 % along with its orientation.
510 % V_k_h(h,k) = sign(h-k)*v(|h-k|)
511 %
512 % Below an auxiliary variable, named "x", will be used.
513 %
514 v=input(' v(|i-j|) = v(x)= ');
515 %
516 % The function handle " v ", inserted by you, corresponds to the weight function v(|i-j|)
517 % that is the handle in x=0 is the weight v(|i-j|) computed in |i-j|=0,
518 % the handle in x=1 is the weight v(|i-j|) computed in |i-j|=1, and so on.
519 %
520 while isa(v,'function_handle')==0
521     disp(' Your input is not a function handle: ')
522     disp(' please follow the instructon above and retype your function. ')
523     v=input(' v(|i-j|) = v(x)= ');
524 end
525 for h=1:classes_number
526     for k=1:classes_number
527         V_k_h(h,k)=sign(h-k)*feval(v,abs(h-k));
528 %
529 % for the matrix V_k_h, 'h' is a row index and 'k' is a column index
530 % and they appear, as parameters, also in the scalar 'abs(h-k)'
531 % which is a non negative integer.
532 %
533 end
534 end
535 V_nan=isnan(V_k_h);
536 V_infinite=isinf(V_k_h);
537 V_real=isreal(V_k_h);
538 while (isequal(V_nan,zeros(classes_number,classes_number))==0 | isequal(V_infinite,zeros(classes_number,classes_number)))
539     V_real==0)
540     disp(char({'',' Note that the function " v(|i-j|) " of the shape you have chosen ',...
541         ' is not defined over the whole domain of the couple (i,j): ',...
542         ' it could invalidate the computation of the Index. ',...
543         ' You can check it by observing the position of all the possible ',...
544         ' NaN values, infinite values or non-real values ',...
545         ' in the following matrix " V_k_h(h,k) " : ','}'))
546     disp(V_k_h)
547     disp(char({'',' So insert a more convenient functional " v(|i-j|) " ',...
548         ' defined for each possible value of the couple (i,j). ',...
549         ' The name "x" for the auxiliary variable is only a suggestion: ','}'))
550 v=input(' v(|i-j|) = v(x)= ');
551 while isa(v,'function_handle')==0
552     disp(' Your input is not a function handle: ')
553     disp(' please follow the instructon above and retype your function. ')
554     v=input(' v(|i-j|) = v(x)= ');
555 end
556 for h=1:classes_number
557     for k=1:classes_number
558         V_k_h(h,k)=sign(h-k)*feval(v,abs(h-k));
559     end
560 end
561 V_nan=isnan(V_k_h);
562 V_infinite=isinf(V_k_h);
563 V_real=isreal(V_k_h);
564 end
565 for Lstart=1:dim(2)-1
566     for Lend=Lstart+1:dim(2)

```

```

567 %
568 Number_k_h_Lstart_Lend(1,1,Lstart,Lend)=sum(MatData(:,Lstart)<=sup(1) & MatData(:,Lend)<=sup(1));
569 %
570 for h=2:classes_number-1
571 Number_k_h_Lstart_Lend(1,h,Lstart,Lend)=sum(MatData(:,Lstart)<=sup(1) &(MatData(:,Lend)>sup(h-1) & MatData(:,Lend)
<=sup(h)));
572 Number_k_h_Lstart_Lend(classes_number,h,Lstart,Lend)=sum(MatData(:,Lstart)>sup(classes_number-1) &(MatData(:,Lend)
>sup(h-1) & MatData(:,Lend)<=sup(h)));
573 end % (for "h")
574 Number_k_h_Lstart_Lend(1,classes_number,Lstart,Lend)=sum(MatData(:,Lstart)<=sup(1) & MatData(:,Lend)>sup
(classes_number-1));
575 %
576 for k=2:classes_number-1
577 Number_k_h_Lstart_Lend(k,1,Lstart,Lend)=sum((MatData(:,Lstart)>sup(k-1) & MatData(:,Lstart)<=sup(k))& MatData(:,Lend)
<=sup(1));
578 Number_k_h_Lstart_Lend(k,classes_number,Lstart,Lend)=sum((MatData(:,Lstart)>sup(k-1) & MatData(:,Lstart)<=sup(k))&
MatData(:,Lend)>sup(classes_number-1));
579 end % (for "k")
580 Number_k_h_Lstart_Lend(classes_number,1,Lstart,Lend)=sum(MatData(:,Lstart)>sup(classes_number-1) & MatData(:,Lend)
<=sup(1));
581 %
582 for h=2:classes_number-1
583 for k=2:classes_number-1
584 Number_k_h_Lstart_Lend(k,h,Lstart,Lend)=sum((MatData(:,Lstart)>sup(k-1) & MatData(:,Lstart)<=sup(k))&(MatData(:,Lend)
>sup(h-1) & MatData(:,Lend)<=sup(h)));
585 end % (for "k")
586 end % (for "h")
587 %
588 Number_k_h_Lstart_Lend(classes_number,classes_number,Lstart,Lend)=sum(MatData(:,Lstart)>sup(classes_number-1) &
MatData(:,Lend)>sup(classes_number-1));
589 end % (for "Lend")
590 end % (for "Lstart")
591 disp(Input0bis)
592 Input6=char({' ',' ' Now this tool is about to begin the computation ' ,...
593 ' of the normalized Directional Mobility Index. ' ,...
594 ' Its value will be calculated respect to the starting period " Tstart " ' ,...
595 ' for one of the subsequent periods " Tend " (Tend > Tstart). ' ,...
596 ' , Please, insert your favorite start " Tstart " , ' ,...
597 ' and indicate it by a positive integer (1,2,..) corresponding ' ,...
598 ' to its location inside the ordered sequence of the observation dates: ');
599 disp(Input6)
600 Tstart=input(' Tstart = ');
601 if (isscalar(Tstart)==0 | isreal(Tstart)==0 | isnan(Tstart)==1 | isinf(Tstart)==1 | not(Tstart>0 & floor(Tstart)==ceil(Tstart) &
Tstart<dim(2)))
602 while (isscalar(Tstart)==0 | isreal(Tstart)==0 | isnan(Tstart)==1 | isinf(Tstart)==1 | not(Tstart>0 & floor(Tstart)==ceil(Tstart)
& Tstart<dim(2)))
603 if (isscalar(Tstart)==0)
604 disp(' ( You pressed the [ENTER] button or inserted a vector or an array ! ) ')
605 disp(' BUT you must insert exclusively a positive integer ! ) ')
606 Tstart=input(' Tstart = ');
607 elseif (isnan(Tstart)==1 | isinf(Tstart)==1 | isreal(Tstart)==0)
608 disp(' Your input is a NaN value or infinite or a complex number: WHY? ')
609 Tstart=input(' Tstart = ');
610 elseif not(Tstart>0 & floor(Tstart)==ceil(Tstart) & Tstart<dim(2))
611 disp(' You must insert a positive integer (1,2,3,...) !! ')
612 Tstart=input(' Tstart = ');
613 elseif Tstart==dim(2)
614 disp(' Your value for Tstart cannot correspond to the last detection !! ')
615 Tstart=input(' Tstart = ');
616 elseif Tstart>dim(2)
617 disp(' Your value for Tstart is too big: there are not enough periods in the data !! ')
618 Tstart=input(' Tstart = ');
619 end
620 end

```

```

621 elseif (isscalar(Tstart)==1 & isreal(Tstart)==1 & isnan(Tstart)==0 & isinf(Tstart)==0 & (Tstart>0 & floor(Tstart)==ceil(
(Tstart) & Tstart<dim(2)))
622 end
623 Input7=char({'',' Insert the finish " Tend " of your interest, ',...
624 ' it also denoted as a progressive positive integer (2,3,...) ',...
625 ' corresponding to its position inside the ordered sequence of dates ',...
626 ' and greater than Tstart: '});
627 disp(Input7)
628 Tend=input('    Tend = ');
629 while (isscalar(Tend)==0 | isreal(Tend)==0 | isnan(Tend)==1 | isinf(Tend)==1 | not(Tend>Tstart & floor(Tend)==ceil(Tend)
& Tend<=dim(2)))
630 if isscalar(Tend)==0
631     disp(' ( You pressed the [ENTER] button or inserted a vector or an array ! ) ')
632     disp(' BUT you must insert exclusively a positive integer ! ) ')
633     Tend=input('    Tend = ');
634 elseif isnan(Tend)==1 | (isinf(Tend)==1 & Tend>dim(2)) | isreal(Tend)==0
635     disp(' Your input is a NaN value or infinite or a complex number: WHY? ')
636     Tend=input('    Tend = ');
637 elseif (Tend<=0|(Tend>0 & floor(Tend)~=ceil(Tend)))
638     disp(' You must insert a positive integer (2,3,4,...) !! ')
639     Tend=input('    Tend = ');
640 elseif Tend<=Tstart
641     disp(' Tend must be greater than Tstart !! ')
642     Tend=input('    Tend = ');
643 elseif Tend>dim(2) & isinf(Tend)==0
644     disp(' Your value for Tend is too big: there are not enough periods !! ')
645     Tend=input('    Tend = ');
646 end
647 end
648 clear Input0bis Input5 default change Input_5bis Input_5ter warn Input6 Input7
649 Output1=char({'',' The weights {w_i} will appear as rows ',...
650 ' inside the array " w_k_Lstart_Lend(k,Lstart,Lend) " ). ',' ,...
651 ' The greatest and the smallest values of the not-normalized Index ',...
652 ' may depend on the initial period "Lstart" and the final one "Lend" ',...
653 ' and will be collected into the 2-dim arrays ',...
654 ' " m1(Lstart,Lend) " and " m2(Lstart,Lend) " respectively. ',...
655 ' All the probabilities are estimated in the classical Laplacian manner !! ',...
656 ' (press [Enter] on the keyboard to begin) ');
657 disp(Output1)
658 response=input(' ','s');
659 while isempty(response)==0
660 disp('(press [Enter] to begin)')
661 response=input(' ','s');
662 end
663 for Lstart=1:dim(2)-1
664     for Lend=Lstart+1:dim(2)
665 m1(Lstart,Lend)=(V_k_h(1,:))*(w_k_Lstart_Lend(:,Lstart,Lend));
666 m2(Lstart,Lend)=(V_k_h(classes_number,:))*(w_k_Lstart_Lend(:,Lstart,Lend));
667     end
668 end
669 %
670 % m1 and m2 are, respectively, the global minimum and the global maximum
671 % theoretically possible for the not-normalized index.
672 % They are necessary to carry out the normalization of the Directional Mobility Index
673 % to the target [-1;+1] in the following manner:
674 %     if the not normalized index is negative then
675 %         normalized index = -1*(not normalized index) / m1;
676 %     else if the not normalized index is non negative then
677 %         normalized index = (not normalized index) / m2;
678 %
679 P_k_h_Tstart_Tend=zeros(classes_number,classes_number);
680 Pup_k_h_Tstart_Tend=zeros(classes_number,classes_number);
681 Pdn_k_h_Tstart_Tend=zeros(classes_number,classes_number);
682 for h=1:classes_number

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```

683 for k=1:classes_number
684 if num_k_Lstart_Lend(k,Tstart,Tend)==0
685 continue
686 end
687 P_k_h_Tstart_Tend(k,h)=(Number_k_h_Lstart_Lend(k,h,Tstart,Tend)./...
688 sum(MatData(:,Tstart)>=lowest_datum & MatData(:,Tend)>=lowest_datum)) ...
689 ./ (num_k_Lstart_Lend(k,Tstart,Tend)./(sum(MatData(:,Tstart)<=highest_datum & isnan_data(:,Tend)==0)));
690 end
691 end
692 for h=1:classes_number
693 for k=1:classes_number
694 if k>=h
695 continue
696 end
697 Pup_k_h_Tstart_Tend(k,h)=P_k_h_Tstart_Tend(k,h);
698 end
699 end
700 for h=1:classes_number
701 for k=1:classes_number
702 if k<=h
703 continue
704 end
705 Pdn_k_h_Tstart_Tend(k,h)=P_k_h_Tstart_Tend(k,h);
706 end
707 end
708 for k=1:classes_number
709 Y_V_k_Tstart_Tend(k)=P_k_h_Tstart_Tend(k,:)*V_k_h(:,k);
710 Yup_V_k_Tstart_Tend(k)=Pup_k_h_Tstart_Tend(k,:)*V_k_h(:,k);
711 Ydn_V_k_Tstart_Tend(k)=Pdn_k_h_Tstart_Tend(k,:)*V_k_h(:,k);
712 ImmobilShares_k_Tstart_Tend(k)=Number_k_h_Lstart_Lend(k,k,Tstart,Tend)./num_tot_Lstart_Lend(Tstart,Tend);
713 end
714 I_w_V_Tstart_Tend=(w_k_Lstart_Lend(:,Tstart,Tend))*Y_V_k_Tstart_Tend(:);
715 Iup_w_V_Tstart_Tend=(w_k_Lstart_Lend(:,Tstart,Tend))*Yup_V_k_Tstart_Tend(:);
716 Idn_w_V_Tstart_Tend=(w_k_Lstart_Lend(:,Tstart,Tend))*Ydn_V_k_Tstart_Tend(:);
717 %
718 % I_w_V_Tstart_Tend = I_w_V_Lstart_Lend(Tstart,Tend)
719 % is the not-normalized version of the Directional Mobility Index.
720 % Iup_w_V_Tstart_Tend = Iup_w_V_Lstart_Lend(Tstart,Tend)
721 % and Idn_w_V_Tstart_Tend = Idn_w_V_Lstart_Lend(Tstart,Tend)
722 % are respectively its upward and downward components.
723 % The new value of the Normalized Directional Mobility Index
724 % Inorm_w_V_Tstart_Tend = Inorm_w_V_Lstart_Lend(Tstart,Tend)
725 % along with its respective upward and downward components
726 % are:
727 %
728 if I_w_V_Tstart_Tend>=0
729 Inorm_w_V_Tstart_Tend=I_w_V_Tstart_Tend./m2(Tstart,Tend);
730 Inorm_up_w_V_Tstart_Tend=Iup_w_V_Tstart_Tend./m2(Tstart,Tend);
731 Inorm_dn_w_V_Tstart_Tend=Idn_w_V_Tstart_Tend./m2(Tstart,Tend);
732 elseif I_w_V_Tstart_Tend<0
733 Inorm_w_V_Tstart_Tend=-I_w_V_Tstart_Tend./m1(Tstart,Tend);
734 Inorm_up_w_V_Tstart_Tend=-Iup_w_V_Tstart_Tend./m1(Tstart,Tend);
735 Inorm_dn_w_V_Tstart_Tend=-Idn_w_V_Tstart_Tend./m1(Tstart,Tend);
736 end
737 UPvsDN_w_V_Tstart_Tend=Iup_w_V_Tstart_Tend./abs(Idn_w_V_Tstart_Tend);
738 disp(' ')
739 Itrace_Tstart_Tend=(classes_number-trace(P_k_h_Tstart_Tend))/(classes_number-1); % Trace index of mobility
740 Idet_Tstart_Tend=1-abs(det(P_k_h_Tstart_Tend)); % Determinant index of mobility
741 [eigenvects_Tstart_Tend,eigenvals_Tstart_Tend]=eig(P_k_h_Tstart_Tend,'vector');
742 abs_eigenvals_Tstart_Tend=abs(eigenvals_Tstart_Tend);
743 sorted_abs_eigenvals_Tstart_Tend=sort(abs_eigenvals_Tstart_Tend,'descend');
744 I2nd_eigval_Tstart_Tend=1-sorted_abs_eigenvals_Tstart_Tend(2); % Mobility index of the 2nd biggest eigenvalue
745 Ieigvals_Tstart_Tend=(classes_number-sum(abs_eigenvals_Tstart_Tend))/(classes_number-1); % All eigenvalues mobility
index

```

```

746 lpredict_Tstart_Tend=classes_number*(sum(sum((P_k_h_Tstart_Tend).^2,2))-1)/(classes_number-1); % Index of predictability
747 for k=1:classes_number
748     w_k_Tstart_Tend(k)=w_k_Lstart_Lend(k,Tstart,Tend);
749     for h=1:classes_number
750         Intensity_k_h(k,h)=abs(h-k);
751     end
752 end
753 BMorrUP_Tstart_Tend=w_k_Tstart_Tend*sum(Pup_k_h_Tstart_Tend,2); % Bourguignon and Morrison Upward Index
754 BMorrDN_Tstart_Tend=w_k_Tstart_Tend*sum(Pdn_k_h_Tstart_Tend,2); % Bourguignon and Morrison Downward Index
755 l_2ndBarthol_Tstart_Tend=(classes_number/(classes_number-1))*(sum(sum(P_k_h_Tstart_Tend.*Intensity_k_h))); % Second ✓
Index of Bartholomew
756 disp(' The value of the normalized Directional Mobility Index, ')
757 fprintf(' from Tstart = %-1.0d to Tend = %-1.0d, is: \n ',Tstart,Tend)
758 fprintf('      Inorm_w_v = %-1.7g \n',Inorm_w_V_Tstart_Tend)
759 disp(char({' ' ' You can compare its value to the ones, for the same transition matrix, ',...
760 ' between the same dates, of some other not-directional mobility indices ',...
761 ' well known in the literature: ',...
762 ' the trace and the determinant indices, " ltrace_Tstart_Tend " and " ldet_Tstart_Tend " ',...
763 ' the All Eigenvalues index, " leigvals_Tstart_Tend " ',...
764 ' and the Second Eigenvalue index, " l2nd_eigval_Tstart_Tend " ',...
765 ' the Index of predictability " lpredict_Tstart_Tend " ',...
766 ' and the Second Index of Bartholomew " l_2ndBarthol_Tstart_Tend " . ',...
767 ' The downward and upward components of the Normalized Directional Index ',...
768 ' will be compared to the Bourguignon-Morrison Downward and Upward Indices, ',...
769 ' indicated as " BMorrDN_Tstart_Tend " and " BMorrUP_Tstart_Tend " . ',...
770 ' Moreover the eigenvalues of the transition matrix " P_k_h_Tstart_Tend " are collected ',...
771 ' in the column vector " eigvals_Tstart_Tend ", whose components correspond orderly, ',...
772 ' one-to-one, to the columns of the matrix " eigenvects_Tstart_Tend ", where are stored ',...
773 ' the relative eigenvectors of " P_k_h_Tstart_Tend " . ',...}'))
774 fprintf('      Inorm_w_v =  %-1.7g \n',Inorm_w_V_Tstart_Tend)
775 fprintf('      ltrace =      %-1.7g \n',ltrace_Tstart_Tend)
776 fprintf('      ldet =        %-1.7g \n',ldet_Tstart_Tend)
777 fprintf('      l2nd_eigval = %-1.7g \n',l2nd_eigval_Tstart_Tend)
778 fprintf('      leigvals =   %-1.7g \n',leigvals_Tstart_Tend)
779 fprintf('      lpredict =    %-1.7g \n',lpredict_Tstart_Tend)
780 fprintf('      l_2ndBarthol = %-1.7g \n',l_2ndBarthol_Tstart_Tend)
781 disp(' ')
782 disp(' The downward and upward components of the normalized Index are respectively: ')
783 fprintf(' Inorm_dn_w_v = %-1.7g \n',Inorm_dn_w_V_Tstart_Tend)
784 fprintf(' Inorm_up_w_v = %-1.7g \n',Inorm_up_w_V_Tstart_Tend)
785 disp(' Compare to the values of the Downward and Upward Morrison-Bourguignon Indices, ')
786 disp(' which are respectively: ')
787 fprintf(' BMorrDN = %-1.7g \n',BMorrDN_Tstart_Tend)
788 fprintf(' BMorrUP = %-1.7g \n',BMorrUP_Tstart_Tend)
789 disp(' ')
790 disp(' The ratio between the upward and the downward components of the Index is: ')
791 fprintf(' UPvsDN_w_V = %-1.7g \n',UPvsDN_w_V_Tstart_Tend)
792 fprintf(' and the percentages of agents remaining into each starting state at Tend=%-1.0d are: \n ',Tend)
793 fprintf(' [ImmobilShare_1,..., ImmobilShare_%-1.0d] = [',classes_number);...
794     fprintf('%-1.5g,',(ImmobilShares_k_Tstart_Tend(1:classes_number-1)));...
795     fprintf('%-1.5g] \n',(ImmobilShares_k_Tstart_Tend(classes_number)))
796 disp(' ')
797 fprintf(' The current values of parameters {w_i, i = 1,...,%-1.0d}, \n',classes_number)
798 disp(' computed from the imported data, in this step are: ')
799 fprintf(' [w_1,..., w_%-1.0d] = [',classes_number);...
800     fprintf('%-1.5g,',(w_k_Lstart_Lend(1:classes_number-1,Tstart,Tend)));...
801     fprintf('%-1.5g] \n',(w_k_Lstart_Lend(classes_number,Tstart,Tend)))
802 Output_zero=char({' ' ' Would you like to see the conditional probability ',...
803 '      " P_k_h_Tstart_Tend " ',...
804 ' that any unit moved from the early k-th class to the h-th one',...
805 ' between Tstart and Tend chosen by you ? ',...
806 ' (Answer "Y" if "yes" or "N" if "not", then press [Enter]) '});
807 disp(Output_zero)
808 answer=input(' ','s');

```

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809 while strcmp(answer,{ 'Y','y','N','n' })==[0,0,0,0]
810     disp(' (You must answer exclusively "Y" or "N" ! ) ')
811     answer=input(' ','s');
812 end
813 if sum(strcmp(answer,{ 'N','n' }))==1
814 disp(char({' Ok: anyway, you can stop this run and quit ',' typing "Ctrl" + "C" on the keyboard. '}))
815 elseif sum(strcmp(answer,{ 'Y','y' }))==1
816 disp(' The transition probability is: ')
817 fprintf(' P_k_h_Tstart_Tend(k,h, Tstart = %-1.0d, Tend = %-1.0d)= \n ',Tstart,Tend)
818 disp(' ')
819 disp(P_k_h_Tstart_Tend)
820 end
821 Output_0bis=char({' ',' Do you want to change the temporal extremes Tstart and Tend ? ','...
822 ' ("Y" for "Yes" or "N" for "Not" then press [Enter]) '});
823 disp(Output_0bis)
824 response=input(' ','s');
825 while strcmp(response,{ 'Y','y','N','n' })==[0,0,0,0]
826     disp(' (You must answer exclusively "Y" or "N" ! ) ')
827     response=input(' ','s');
828 end
829 if sum(strcmp(response,{ 'N','n' }))==1
830 clear Output_zero Output_0bis Output1 Output_1bis answer response resp
831 elseif sum(strcmp(response,{ 'Y','y' }))==1
832 while sum(strcmp(response,{ 'Y','y' }))==1
833     clear Tstart Tend
834 Input_6bis=char({' ',' Insert the new start " Tstart " , ','...
835 ' indicating it by a positive integer corresponding to its location ','...
836 ' inside the ordered sequence of the observations: '});
837 disp(Input_6bis)
838 Tstart=input(' Tstart = ');
839 if (isscalar(Tstart)==0 | isreal(Tstart)==0 | isnan(Tstart)==1 | isinf(Tstart)==1 | not(Tstart>0 & floor(Tstart)==ceil(Tstart) &
Tstart<dim(2)))
840 while (isscalar(Tstart)==0 | isreal(Tstart)==0 | isnan(Tstart)==1 | isinf(Tstart)==1 | not(Tstart>0 & floor(Tstart)==ceil(Tstart)
& Tstart<dim(2)))
841     if (isscalar(Tstart)==0)
842         disp(' ( You pressed the [ENTER] button or inserted a vector or an array ! ) ')
843         disp(' BUT you must insert exclusively a positive integer ! ) ')
844         Tstart=input(' Tstart = ');
845     elseif (isnan(Tstart)==1 | isinf(Tstart)==1 | isreal(Tstart)==0)
846         disp(' Your input is a NaN value or infinite or a complex number: WHY? ')
847         Tstart=input(' Tstart = ');
848     elseif not(Tstart>0 & floor(Tstart)==ceil(Tstart) & Tstart<dim(2))
849         disp(' You must insert a positive integer (1,2,3,...) !! ')
850         Tstart=input(' Tstart = ');
851     elseif Tstart==dim(2)
852         disp(' Your value for Tstart cannot correspond to the last detection !! ')
853         Tstart=input(' Tstart = ');
854     elseif Tstart>dim(2)
855         disp(' Your value for Tstart is too big: there are not enough periods in the data !! ')
856         Tstart=input(' Tstart = ');
857     end
858 end
859 elseif (isscalar(Tstart)==1 & isreal(Tstart)==1 & isnan(Tstart)==0 & isinf(Tstart)==0 & (Tstart>0 & floor(Tstart)==ceil
(Tstart) & Tstart<dim(2)))
860 end
861 Input_7bis=char({' Then, insert the new finish " Tend " ','...
862 ' it also denoted as a progressive positive integer ','...
863 ' according to its position inside the ordered sequence of dates ','...
864 ' and greater than Tstart: '});
865 disp(Input_7bis)
866 Tend=input(' Tend = ');
867 while (isscalar(Tend)==0 | isreal(Tend)==0 | isnan(Tend)==1 | isinf(Tend)==1 | not(Tend>Tstart & floor(Tend)==ceil(Tend)
& Tend<=dim(2)))
868 if isscalar(Tend)==0

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869 disp(' ( You pressed the [ENTER] button or inserted a vector or an array ! ) ')
870 disp(' BUT you must insert exclusively a positive integer ! ) ')
871 Tend=input(' Tend = ');
872 elseif isnan(Tend)==1 | (isinf(Tend)==1 & Tend>dim(2)) | isreal(Tend)==0
873     disp(' Your input is a NaN value or infinite or a complex number: WHY? ')
874     Tend=input(' Tend = ');
875 elseif (Tend<=0|(Tend>0 & floor(Tend)~=ceil(Tend)))
876 disp(' You must insert a positive integer (2,3,4,...) !! ')
877 Tend=input(' Tend = ');
878 elseif Tend<=Tstart
879 disp(' Tend must be greater than Tstart !! ')
880 Tend=input(' Tend = ');
881 elseif Tend>dim(2) & isinf(Tend)==0
882 disp(' Your value for Tend is too big: there are not enough periods !! ')
883 Tend=input(' Tend = ');
884 end
885 end
886 Output_1bis=char({'',' Press [Enter] on the keyboard ',' to recompute the Index between the new extremes ','...
887 '(it would be better to take a note of its previous value, ','...
888 ' displayed inside the Command Window, ','...
889 ' and not to command "clc" after exiting. '););
890 disp(Output_1bis)
891 response=input(' ','s');
892 while isempty(response)==0
893 disp('(press [Enter] to begin)')
894 response=input(' ','s');
895 end
896 P_k_h_Tstart_Tend=zeros(classes_number,classes_number);
897 Pup_k_h_Tstart_Tend=zeros(classes_number,classes_number);
898 Pdn_k_h_Tstart_Tend=zeros(classes_number,classes_number);
899 for h=1:classes_number
900     for k=1:classes_number
901         if num_k_Lstart_Lend(k,Tstart,Tend)==0
902             continue
903         end
904         P_k_h_Tstart_Tend(k,h)=(Number_k_h_Lstart_Lend(k,h,Tstart,Tend)./...
905             sum(MatData(:,Tstart)>=lowest_datum & MatData(:,Tend)>=lowest_datum)) ...
906             ./ (num_k_Lstart_Lend(k,Tstart,Tend)./(sum(MatData(:,Tstart)<=highest_datum & isnan_data(:,Tend)==0)));
907     end
908 end
909 for h=1:classes_number
910     for k=1:classes_number
911         if k>=h
912             continue
913         end
914         Pup_k_h_Tstart_Tend(k,h)=P_k_h_Tstart_Tend(k,h);
915     end
916 end
917 for h=1:classes_number
918     for k=1:classes_number
919         if k<=h
920             continue
921         end
922         Pdn_k_h_Tstart_Tend(k,h)=P_k_h_Tstart_Tend(k,h);
923     end
924 end
925 for k=1:classes_number
926     Y_V_k_Tstart_Tend(k)=P_k_h_Tstart_Tend(k,:)*V_k_h(:,k);
927     Yup_V_k_Tstart_Tend(k)=Pup_k_h_Tstart_Tend(k,:)*V_k_h(:,k);
928     Ydn_V_k_Tstart_Tend(k)=Pdn_k_h_Tstart_Tend(k,:)*V_k_h(:,k);
929     ImmobilShares_k_Tstart_Tend(k)=Number_k_h_Lstart_Lend(k,k,Tstart,Tend)./num_tot_Lstart_Lend(Tstart,Tend);
930 end
931 l_w_V_Tstart_Tend=(w_k_Lstart_Lend(:,Tstart,Tend))*Y_V_k_Tstart_Tend(:);
932 lup_w_V_Tstart_Tend=(w_k_Lstart_Lend(:,Tstart,Tend))*Yup_V_k_Tstart_Tend(:);

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933 ldn_w_V_Tstart_Tend=(w_k_Lstart_Lend(:,Tstart,Tend))*Ydn_V_k_Tstart_Tend(:);
934 %
935 % The new value of the Normalized Directional Mobility Index
936 % Inorm_w_V_Tstart_Tend = Inorm_w_V_Lstart_Lend(Tstart,Tend)
937 % along with its respective upward and downward components
938 % are:
939 %
940 if l_w_V_Tstart_Tend>=0
941     Inorm_w_V_Tstart_Tend=l_w_V_Tstart_Tend./m2(Tstart,Tend);
942     Inorm_up_w_V_Tstart_Tend=lup_w_V_Tstart_Tend./m2(Tstart,Tend);
943     Inorm_dn_w_V_Tstart_Tend=ldn_w_V_Tstart_Tend./m2(Tstart,Tend);
944 elseif l_w_V_Tstart_Tend<0
945     Inorm_w_V_Tstart_Tend=-l_w_V_Tstart_Tend./m1(Tstart,Tend);
946     Inorm_up_w_V_Tstart_Tend=-lup_w_V_Tstart_Tend./m1(Tstart,Tend);
947     Inorm_dn_w_V_Tstart_Tend=-ldn_w_V_Tstart_Tend./m1(Tstart,Tend);
948 end
949 UPvsDN_w_V_Tstart_Tend=lup_w_V_Tstart_Tend./abs(ldn_w_V_Tstart_Tend);
950 disp(' ')
951 ltrace_Tstart_Tend=(classes_number-trace(P_k_h_Tstart_Tend))/(classes_number-1);
952 ldet_Tstart_Tend=1-abs(det(P_k_h_Tstart_Tend));
953 [eigenvecs_Tstart_Tend,eigenvals_Tstart_Tend]=eig(P_k_h_Tstart_Tend,'vector');
954 abs_eigenvals_Tstart_Tend=abs(eigenvals_Tstart_Tend);
955 sorted_abs_eigenvals_Tstart_Tend=sort(abs_eigenvals_Tstart_Tend,'descend');
956 l2nd_eigval_Tstart_Tend=1-sorted_abs_eigenvals_Tstart_Tend(2);
957 leigvals_Tstart_Tend=(classes_number-sum(abs_eigenvals_Tstart_Tend))/(classes_number-1);
958 lpredict_Tstart_Tend=classes_number*(sum(sum((P_k_h_Tstart_Tend).^2,2))-1)/(classes_number-1);
959 for k=1:classes_number
960     w_k_Tstart_Tend(k)=w_k_Lstart_Lend(k,Tstart,Tend);
961 end
962 BMorrUP_Tstart_Tend=w_k_Tstart_Tend*sum(Pup_k_h_Tstart_Tend,2);
963 BMorrDN_Tstart_Tend=w_k_Tstart_Tend*sum(Pdn_k_h_Tstart_Tend,2);
964 l_2ndBarthol_Tstart_Tend=(classes_number/(classes_number-1))*(sum(sum(P_k_h_Tstart_Tend.*Intensity_k_h)));
965 disp(' The value of the normalized Directional Mobility Index, ')
966 fprintf(' from Tstart = %-1.0d to Tend = %-1.0d, is: \n ',Tstart,Tend)
967 fprintf(' Inorm_w_v = %-1.7g \n',Inorm_w_V_Tstart_Tend)
968 disp(char({'',' Compare it, for the same transition matrix and between the same dates, ','...
969 ' to the other not-directional mobility indices ','}'))
970 fprintf(' Inorm_w_v = %-1.7g \n',Inorm_w_V_Tstart_Tend)
971 fprintf(' ltrace = %-1.7g \n',ltrace_Tstart_Tend)
972 fprintf(' ldet = %-1.7g \n',ldet_Tstart_Tend)
973 fprintf(' l2nd_eigval = %-1.7g \n',l2nd_eigval_Tstart_Tend)
974 fprintf(' leigvals = %-1.7g \n',leigvals_Tstart_Tend)
975 fprintf(' lpredict = %-1.7g \n',lpredict_Tstart_Tend)
976 fprintf(' l_2ndBarthol = %-1.7g \n',l_2ndBarthol_Tstart_Tend)
977 disp(' ')
978 disp(' The downward and upward components of the normalized Index are respectively: ')
979 fprintf(' Inorm_dn_w_v = %-1.7g \n',Inorm_dn_w_V_Tstart_Tend)
980 fprintf(' Inorm_up_w_v = %-1.7g \n',Inorm_up_w_V_Tstart_Tend)
981 disp(' Compare to the values of the Downward and Upward Morrison-Bourguignon Indices, ')
982 disp(' which are respectively: ')
983 fprintf(' BMorrDN = %-1.7g \n',BMorrDN_Tstart_Tend)
984 fprintf(' BMorrUP = %-1.7g \n',BMorrUP_Tstart_Tend)
985 disp(' ')
986 disp(' The ratio between the upward and the downward components of the Index is: ')
987 fprintf(' UPvsDN_w_V = %-1.7g \n',UPvsDN_w_V_Tstart_Tend)
988 fprintf(' and the percentages of agents remaining into each starting state at Tend=%-1.0d are: \n ',Tend)
989 fprintf(' [ImmobilShare_1,..., ImmobilShare_%-1.0d] = [',classes_number);...
990     fprintf('%-1.5g,',(ImmobilShares_k_Tstart_Tend(1:classes_number-1)));...
991     fprintf('%-1.5g] \n',(ImmobilShares_k_Tstart_Tend(classes_number)))
992 disp(' ')
993 fprintf(' The current values of parameters {w_i, i = 1,...,%-1.0d}, \n',classes_number)
994 disp(' computed from the imported data, in this step are: ')
995 fprintf(' [w_1,..., w_%-1.0d] = [',classes_number);...
996     fprintf('%-1.5g,',(w_k_Lstart_Lend(1:classes_number-1,Tstart,Tend)));...

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997         fprintf('%-1.5g] \n',(w_k_Lstart_Lend(classes_number,Tstart,Tend)))
998 clear Input_6bis Input_7bis Output1 Output_1bis
999 Output_1ter=char({'',' Would you like to see the new transition probability ',...
1000 '         " P_k_h_Tstart_Tend " ',...
1001 ' that a unit moved from the k-th class to the h-th one',...
1002 ' between the new pair (Tstart, Tend) ? ',...
1003 ' (Answer "Y" if "yes" or "N" if "not", then press [Enter]) '});
1004 disp(Output_1ter)
1005 answer=input(' ','s');
1006 while strcmp(answer,{'Y','y','N','n'})==[0,0,0,0]
1007     disp(' (You must answer exclusively "Y" or "N" !) ')
1008     answer=input(' ','s');
1009 end
1010 if sum(strcmp(answer,{'N','n'}))==1
1011 disp(char({' Ok: anyway, you can stop this run and quit ',' typing "Ctrl" + "C" on the keyboard. '}))
1012 elseif sum(strcmp(answer,{'Y','y'}))==1
1013 disp(' The new transition probability is: ')
1014 fprintf(' P_k_h_Lstart_Lend(k,h, Tstart = %-1.0d, Tend = %-1.0d)= \n ',Tstart,Tend)
1015 disp(' ')
1016 disp(P_k_h_Tstart_Tend)
1017 end
1018 disp(Output_0bis)
1019 response=input(' ','s');
1020 while strcmp(response,{'Y','y','N','n'})==[0,0,0,0]
1021     disp(' (You must answer exclusively "Y" or "N" !) ')
1022     response=input(' ','s');
1023 end
1024 end
1025 clear abs_eigenvals_Tstart_Tend sorted_abs_eigenvals_Tstart_Tend
1026 Output_1quater=char({'',' Are you interested in knowing, ',...
1027 ' for every possible pair (Lstart,Lend), ',...
1028 ' all the transition matrices ',...
1029 ' and all the values of the Index ? ',...
1030 ' (Answer "Y" if "yes" or "N" if "not", then press [Enter]) '});
1031 disp(Output_1quater)
1032 resp=input(' ','s');
1033 while strcmp(resp,{'Y','y','N','n'})==[0,0,0,0]
1034     disp(' (You must answer exclusively "Y" or "N" !) ')
1035     resp=input(' ','s');
1036 end
1037 clear Output_zero Output_0bis Output1 Output_1bis Output_1ter Output_1quater
1038 Output2=char({'',' In the workspace, you could find an array, ',...
1039 ' depending only on (Lstart,Lend) and named: ',...
1040 '         " Inorm_w_V_Lstart_Lend " ',...
1041 ' where 1 <= Lstart <= dim(2)-1 ',...
1042 ' and 1 <= Lend <= dim(2) . ',' as well as other related outputs. ',...
1043 ' Remember: dim(2) is the number of all observation dates in your data. ',...
1044 ' Logically "Lend" should be such that Lstart+1 <= Lend <= dim(2) ',...
1045 ' but Matlab tends by default to complete inwards the indefinite positions ',...
1046 ' inside the arrays using zeros, so as they are rectangular anyway. ',...
1047 ' As a consequence, the first column in " Inorm_w_V_Lstart_Lend " ',...
1048 ' corresponds to " Lstart=1 and Lend=1 " and it is made up of zeros. ',...
1049 ' At the positions for 1 <= Lstart <= dim(2)-1 and Lstart+1 <= Lend <= dim(2) ',...
1050 ' the matrices " Inorm_w_V_Lstart_Lend ", " Inorm_up_w_V_Lstart_Lend ", ...
1051 ' " Inorm_dn_w_V_Lstart_Lend " are composed by the normalized index's values, ',...
1052 ' the values of its upward part and its downward one. ',...
1053 ' Elsewhere the elements of these matrices are zeros. '});
1054 Output2_2=char({' Fixing "Lstart", you have fixed a row; ',' fixing "Lend", you have fixed a column. ',...
1055 ' When Lstart > Lend, it is an impossible case, ',...
1056 ' and if Lstart = Lend there is not any transition: ',...
1057 ' thus the total mobility associated to both of these cases is zero! ',...
1058 ',' After completing the current run, you can still display ',...
1059 ' anyone of the outputs, linked to the Directional Index, ',...
1060 ' just typing its name into the keyboard in the MATLAB Command Window, ',...

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1061 ' for instance " Inorm_w_V_Lstart_Lend ". ',...
1062 ',' Such directional mobility output are listed below : ',...
1063 ' the not-normalized directional mobility index " I_w_V_Lstart_Lend " ',...
1064 ' along with its upward and downward parts ',' " Iup_w_V_Lstart_Lend " and " Idn_w_V_Lstart_Lend " ',...
1065 ' and the upward and downward parts of the normalized index ',...
1066 ' " Inorm_up_w_V_Lstart_Lend " and " Inorm_down_w_V_Lstart_Lend "; ',...
1067 ' the share of unmoving individuals at class "i" ',...
1068 ' over the numerosity of the entire sample, ',' " ImmobilShares_k_Lstart_Lend ", ',...
1069 ' the upward versus downward partial mobilities ratio " UPvsDN_w_V_Lstart_Lend ". ');
1070 Output3=char({' We have named as: ',...
1071 ' " P_k_h_Lstart_Lend(k,h,Lstart,Lend) " ',...
1072 ' the probability that an individual in the sample may make a transition ',...
1073 ' from the k-th class at the time "Lstart" to the h-th class at the final period "Lend". ');
1074 Output3_2=char({' After getting out of this tool, it is also possible to visualize, ',...
1075 ' for the current session, the transition probabilities" matrix typing ',...
1076 ' " P_k_h_Lstart_Lend(:,Lstart,Lend) " ',...
1077 ' for specific couples of values of (Lstart,Lend). ');
1078 P_k_h_Lstart_Lend=zeros(classes_number,classes_number,dim(2)-1,dim(2)-1);
1079 Pup_k_h_Lstart_Lend=zeros(classes_number,classes_number,dim(2)-1,dim(2)-1);
1080 Pdn_k_h_Lstart_Lend=zeros(classes_number,classes_number,dim(2)-1,dim(2)-1);
1081 for Lstart=1:dim(2)-1
1082 for Lend=Lstart+1:dim(2)
1083 for h=1:classes_number
1084 for k=1:classes_number
1085 if num_k_Lstart_Lend(k,Lstart,Lend)==0
1086 continue
1087 end
1088 P_k_h_Lstart_Lend(k,h,Lstart,Lend)=(Number_k_h_Lstart_Lend(k,h,Lstart,Lend)./...
1089 sum(MatData(:,Lstart)>=lowest_datum & MatData(:,Lend)>=lowest_datum)) ...
1090 ./((num_k_Lstart_Lend(k,Lstart,Lend)./(sum(MatData(:,Lstart)<=highest_datum & isnan_data(:,Lend)==0))));
1091 % After fixing "Lstart" and "Lend", P_k_h_Lstart_Lend is a matrix,
1092 % 'k' is a row index, 'h' is a column index.
1093 end
1094 end
1095 end
1096 end
1097 for Lstart=1:dim(2)-1
1098 for Lend=Lstart+1:dim(2)
1099 for h=1:classes_number
1100 for k=1:classes_number
1101 if k>=h
1102 continue
1103 end
1104 Pup_k_h_Lstart_Lend(k,h,Lstart,Lend)=P_k_h_Lstart_Lend(k,h,Lstart,Lend);
1105 end
1106 end
1107 for h=1:classes_number
1108 for k=1:classes_number
1109 if k<=h
1110 continue
1111 end
1112 Pdn_k_h_Lstart_Lend(k,h,Lstart,Lend)=P_k_h_Lstart_Lend(k,h,Lstart,Lend);
1113 end
1114 end
1115 end
1116 end
1117 for Lstart=1:dim(2)-1
1118 for Lend=Lstart+1:dim(2)
1119 for k=1:classes_number
1120 Y_V_k_Lstart_Lend(k,Lstart,Lend)=P_k_h_Lstart_Lend(k,:,Lstart,Lend)*V_k_h(:,k);
1121 Yup_V_k_Lstart_Lend(k,Lstart,Lend)=Pup_k_h_Lstart_Lend(k,:,Lstart,Lend)*V_k_h(:,k);
1122 Ydn_V_k_Lstart_Lend(k,Lstart,Lend)=Pdn_k_h_Lstart_Lend(k,:,Lstart,Lend)*V_k_h(:,k);
1123 ImmobilShares_k_Lstart_Lend(k,Lstart,Lend)=Number_k_h_Lstart_Lend(k,k,Lstart,Lend)./num_tot_Lstart_Lend(Lstart,Lend);
1124 end

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1125 I_w_V_Lstart_Lend(Lstart,Lend)=(w_k_Lstart_Lend(:,Lstart,Lend))*Y_V_k_Lstart_Lend(:,Lstart,Lend);
1126 Iup_w_V_Lstart_Lend(Lstart,Lend)=(w_k_Lstart_Lend(:,Lstart,Lend))*Yup_V_k_Lstart_Lend(:,Lstart,Lend);
1127 Idn_w_V_Lstart_Lend(Lstart,Lend)=(w_k_Lstart_Lend(:,Lstart,Lend))*Ydn_V_k_Lstart_Lend(:,Lstart,Lend);
1128 %
1129 %   The array of the Normalized Directional Mobility Index
1130 %       Inorm_w_V_Lstart_Lend(Lstart,Lend),
1131 %   along with the respective upward and downward components
1132 %       Inorm_up_w_V_Lstart_Lend(Lstart,Lend)
1133 %       and Inorm_dn_w_V_Lstart_Lend(Lstart,Lend),
1134 %   (where, in all cases, Lstart is a row index and Lend is a column index)
1135 %   are:
1136 %
1137 if I_w_V_Lstart_Lend(Lstart,Lend)>=0
1138     Inorm_w_V_Lstart_Lend(Lstart,Lend)=I_w_V_Lstart_Lend(Lstart,Lend)./m2(Lstart,Lend);
1139     Inorm_up_w_V_Lstart_Lend(Lstart,Lend)=Iup_w_V_Lstart_Lend(Lstart,Lend)./m2(Lstart,Lend);
1140     Inorm_dn_w_V_Lstart_Lend(Lstart,Lend)=Idn_w_V_Lstart_Lend(Lstart,Lend)./m2(Lstart,Lend);
1141 elseif I_w_V_Lstart_Lend(Lstart,Lend)<0
1142     Inorm_w_V_Lstart_Lend(Lstart,Lend)=-I_w_V_Lstart_Lend(Lstart,Lend)./m1(Lstart,Lend);
1143     Inorm_up_w_V_Lstart_Lend(Lstart,Lend)=-Iup_w_V_Lstart_Lend(Lstart,Lend)./m1(Lstart,Lend);
1144     Inorm_dn_w_V_Lstart_Lend(Lstart,Lend)=-Idn_w_V_Lstart_Lend(Lstart,Lend)./m1(Lstart,Lend);
1145 end
1146 UPvsDN_w_V_Lstart_Lend(Lstart,Lend)=Iup_w_V_Lstart_Lend(Lstart,Lend)./abs(Idn_w_V_Lstart_Lend(Lstart,Lend));
1147 end
1148 end
1149 if sum(strcmp(resp,{'Y','y'}))==1
1150 disp(Output2)
1151 disp(char({' It is: ',      Inorm_w_V_Lstart_Lend = ', ' }'))
1152 disp(Inorm_w_V_Lstart_Lend)
1153 disp('      (Press "Enter" to go on) ')
1154 response=input(' ','s');
1155 while isempty(response)==0
1156 disp('   Please, press just "Enter" to go on.')
1157 response=input(' ','s');
1158 end
1159 disp(Output2_2)
1160 disp('(Press [Enter] to move towards a conclusion...)');
1161 response=input(' ','s');
1162 while isempty(response)==0
1163 disp('(Press [Enter] to move towards a conclusion...)')
1164 response=input(' ','s');
1165 end
1166 disp(Output3)
1167 disp(Output3_2)
1168 clear Output2 Output2_2 Output3 Output3_2 response answer resp
1169 elseif sum(strcmp(resp,{'N','n'}))==1
1170     disp(Output2)
1171     disp(char({' DO YOU WANT TO CANCEL IT ? ',...
1172 ' (Press "Y" for "yes" or "N" for "not", then [Enter]) '}))
1173     last_ans=input(' ','s');
1174     while strcmp(last_ans,{'Y','y','N','n'})==[0,0,0,0]
1175         disp(' (You must answer exclusively "Y" or "N" !) ')
1176         last_ans=input(' ','s');
1177     end
1178     if sum(strcmp(last_ans,{'Y','y'}))==1
1179         clear Y_V_k_Lstart_Lend Yup_V_k_Lstart_Lend Ydn_V_k_Lstart_Lend
1180         clear I_w_V_Lstart_Lend Iup_w_V_Lstart_Lend Idn_w_V_Lstart_Lend
1181         clear Inorm_w_V_Lstart_Lend Inorm_up_w_V_Lstart_Lend Inorm_dn_w_V_Lstart_Lend
1182         clear ImmobilShares_k_Lstart_Lend UPvsDN_w_V_Lstart_Lend
1183     elseif sum(strcmp(last_ans,{'N','n'}))==1
1184         disp(Output2_2)
1185     end
1186     disp(Output3)
1187     disp(char({' DO YOU WANT TO CANCEL ALL THESE MATRICES ? ',...
1188 ' (Press "Y" for "yes" or "N" for "not", then [Enter]) '}))

```

```

1189 last_ans=input(' ','s');
1190 while strcmp(last_ans',{'Y','y','N','n'})==[0,0,0,0]
1191     disp(' (You must answer exclusively "Y" or "N" ! )')
1192     last_ans=input(' ','s');
1193 end
1194 if sum(strcmp(last_ans',{'Y','y'}))==1
1195     clear P_k_h_Lstart_Lend Pup_k_h_Lstart_Lend Pdn_k_h_Lstart_Lend
1196 elseif sum(strcmp(last_ans',{'N','n'}))==1
1197     disp(' ')
1198     disp(Output3_2)
1199 Output3_3=char({' If Lstart > Lend, it is an impossible case, ',...
1200 ' and if Lstart = Lend there is not any transition, ',...
1201 ' so all the transition probability associated to those cases ',...
1202 ' are zero for each couple of state (k,h)! '});
1203     disp(Output3_3)
1204 end
1205 clear Output2 Output2_2 Output3 Output3_2 Output3_3 answer response resp last_ans
1206 end
1207 clear Output2 Output2_2 Output3 Output3_2 Output3_3 answer response resp last_ans
1208 end
1209 clear Output2 Output2_2 Output3 Output3_2 Output3_3 answer response resp last_ans
1210 Ending1=char({' ',' ' In the MATLAB workspace there are listed all your input parameters ',...
1211 ' and all the arrays served for the estimation of the Directional Index"s values ',...
1212 ' with the relative transition matrices. ',...
1213 ' To know the meaning of the other auxiliary arrays, like "m1" and "m2", ',...
1214 ' " Number_k_h_Lstart_Lend " , " num_k_Lstart_Lend " or " Y_V_k_Tstart_Tend " ',...
1215 ' you can refer to the text notes included in the script "DMMtool.m" ',...
1216 ' or to the related paper by Aringhieri, Ferretti, Ganugi. ',...
1217 ' If you want to recompute the Directional Mobility Index ',...
1218 ' in case of a different shape of the function " v(|j-i|) " , ',...
1219 ' a different definition of the set of states or of the weights {w_i}, ',...
1220 ' it is necessary to restart "DMMtool.m" for a new session in MATLAB. '});
1221 disp(Ending1)
1222 Ending2=char({' ' So this session is going to terminate: ',...
1223 ' you will return directly to the prompt state ',...
1224 ' after pressing [Enter] on your keyboard ! '});
1225 disp(Ending2)
1226 response=input(' ','s');
1227 while isempty(response)==0
1228     disp('(press [Enter] to exit from "DMMtool.m")')
1229     response=input(' ','s');
1230 end
1231 clear Ending1 Ending2 k h Tstart Tend Lstart Lend response resp_w
1232 return

```